## Example

$A=\forall x \forall y(q(x, y) \rightarrow(p(x, y) \vee \exists z(p(x, z) \wedge q(z, y))$
Take the tructure $M=$ (people, $\{q \mapsto$ ancestor, $p \mapsto$ parent $\}, \emptyset, \emptyset)$ and any value assignment $s$ :

- $v_{M, s}(\forall x \forall y(q(x, y) \rightarrow(p(x, y) \vee \exists z(p(x, z) \wedge q(z, y)))))=1$ iff
- for all $d \in D$,
$v_{M, s[x \leftarrow d]}(\forall y(q(x, y) \rightarrow(p(x, y) \vee \exists z(p(x, z) \wedge q(z, y)))))=1$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, $v_{M, s[x \leftarrow d]\left[y \leftarrow d^{\prime}\right]}(q(x, y) \rightarrow(p(x, y) \vee \exists z(p(x, z) \wedge q(z, y))))=1$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, if $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]}(q(x, y))=1$ then $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]}(p(x, y) \vee \exists z(p(x, z) \wedge q(z, y)))=1$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, if $\left(d, d^{\prime}\right) \in$ ancestor then either $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]}(p(x, y))$ or $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]}(\exists z(p(x, z) \wedge q(z, y)))$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, if $\left(d, d^{\prime}\right) \in$ ancestor then either $\left(d, d^{\prime}\right) \in$ parent or there exists a $d^{\prime \prime} \in D$, such that $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]\left[z \mapsto d^{\prime \prime}\right]}(p(x, z) \wedge q(z, y))=1$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, if $\left(d, d^{\prime}\right) \in$ ancestor then either $\left(d, d^{\prime}\right) \in$ parent or there exists a $d^{\prime \prime} \in D$, such that $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]\left[z \mapsto d^{\prime \prime}\right]}(p(x, z))=1$ and $v_{M, s[x \mapsto d]\left[y \mapsto d^{\prime}\right]\left[z \mapsto d^{\prime \prime}\right]}(q(z, y))=1$ iff
- for all $d \in D$, for all $d^{\prime} \in D$, if $\left(d, d^{\prime}\right) \in$ ancestor then either $\left(d, d^{\prime}\right) \in$ parent or there exists a $d^{\prime \prime} \in D$, such that $\left(d, d^{\prime \prime}\right) \in$ parent and


## Literal, clause

- Literal: either an atom $p$ (positive literal) or its negation $\neg p$ (negative literal).
- The complementary literal to $L$ :

$$
L \stackrel{\text { def }}{\Leftrightarrow} \begin{cases}\neg L, & \text { if } L \text { is positive; } \\ p, & \text { if } L \text { has the form } \neg p .\end{cases}
$$

In other words, $p$ and $\neg p$ are complementary.

- Clause: a disjunction $L_{1} \vee \ldots \vee L_{n}, n \geq 0$ of literals.
- Empty clause, denoted by $\square: n=0$ (the empty clause is false in every interpretation).
- Unit clause: $n=1$.

When we consider clauses we assume that the order of literals in them is irrelevant.

## Negation Normal Form

A formula $A$ is in negation normal form, or simply NNF, if it is either $T$, or $\perp$, or is built from literals using only $\wedge, \vee, \forall$ and $\exists$.

A formula $B$ is called a negation normal form of a formula $A$ if $B$ is equivalent to $A$ and $B$ is in negation normal form.

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## NNF transformation

$$
\begin{aligned}
A \leftrightarrow B & \Rightarrow(\neg A \vee B) \wedge(\neg B \vee A), \\
A \rightarrow B & \Rightarrow \neg A \vee B, \\
\neg(A \wedge B) & \Rightarrow \neg A \vee \neg B, \\
\neg(A \vee B) & \Rightarrow \neg A \wedge \neg B, \\
\neg(\forall x) A & \Rightarrow(\exists x) \neg A, \\
\neg(\exists x) A & \Rightarrow(\forall x) \neg A, \\
\neg \neg A & \Rightarrow A
\end{aligned}
$$

## Rectified formulas

Rectified formula F:

- no variable appears both free and bound in $F$;
- for every variable $x$, the formula $F$ contains at most one occurrence of quantifiers $\forall x$ or $\exists x$.
Any formula can be transformed into a rectified formula by renaming bound variables.


## Rectification: Example

$$
\begin{aligned}
& p(x) \rightarrow \exists x(p(x) \wedge \forall x(p(x) \vee r \rightarrow \neg p(x))) \Rightarrow \\
& p(x) \rightarrow \exists x_{1}\left(p\left(x_{1}\right) \wedge \forall x(p(x) \vee r \rightarrow \neg p(x))\right) \Rightarrow \\
& p(x) \rightarrow \exists x_{1}\left(p\left(x_{1}\right) \wedge \forall x_{2}\left(p\left(x_{2}\right) \vee r \rightarrow \neg p\left(x_{2}\right)\right)\right)
\end{aligned}
$$

## Skolemisation: Choice Functions

We would like to get rid of existential quantifiers using choice functions, or witness functions.
Consider an example. We know that every tree has a root:

$$
\begin{equation*}
\forall x(\operatorname{tree}(x) \rightarrow \exists y(\operatorname{root}(y, x))) . \tag{*}
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$$

Then we can introduce a function, say rootof that gives the root of a tree and write

Note that $(*)$ is a logical consequence of

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$$
\begin{equation*}
\forall x(\operatorname{tree}(x) \rightarrow \operatorname{root}(\operatorname{rootof}(x), x)) \tag{**}
\end{equation*}
$$

Note that $(*)$ is a logical consequence of $(* *)$.

## Skolemisation

Let $A$ be a closed rectified formula in NNF and $(\exists x) B$ be a subformula of $A$. Let $\left(\forall x_{1}\right), \ldots,\left(\forall x_{n}\right)$ be all universal quantifiers such that $(\exists x) B$ is in the scope of these quantifiers. Then:

1. remove $(\exists x)$ from $A$.
2. replace $x$ everywhere in $A$ by $f\left(x_{1}, \ldots, x_{n}\right)$, where $f$ is a new function symbol.
Skolemisation does not preserve equivalence but preserves satisfiability.

## CNF Transformation

Take a first-order formula $F$.

1. transform it into NNF;
2. rectify it;
3. skolemise it;
4. remove all universal quantifiers;
5. transform to CNF the same way as propositional formulas.

## CNF Transformation

Universal closure of a formula $A$ is a formula

$$
\left(\forall x_{1}\right) \ldots\left(\forall x_{n}\right) A,
$$

denoted by $\forall A$, where $x_{1}, \ldots, x_{n}$ are all free variables of $A$.
CNF transformation transforms a closed formula $F$ into a set of clauses $C_{1}, \ldots, C_{n}$ such that $F$ is satisfiable if and only if so is the set of formulas $\forall C_{1}$.

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## Example

Suppose we want to prove (establish validity of)

$$
(\exists y)(\forall x) p(x, y) \rightarrow(\forall x)(\exists y) p(x, y)
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## is unsatisfiable.

The transformation of this formula to CNF gives us two clauses:

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How can we check unsatisfiability of

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## Ideas

Note that we established unsatisfiability by

- Substituting terms for variables, e.g. $b$ for $x$ in $p(x, a)$;
- Using propositional resolution.


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Are these two ingredients sufficient to have a complete procedure?

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\theta(x)= \begin{cases}t_{i} & \text { if } x=x_{i} ; \\ x & \text { if } x \notin\left\{x_{1}, \ldots, x_{n}\right\} .\end{cases}
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- Application of this substitution to an expression $E$ : simultaneous replacement of $x_{i}$ by $t_{i}$.
- The result of the application of a substitution $\theta$ to $E$ is denoted by E $\theta$.
- Since substitutions are functions, we can define their composition (writen $\sigma \tau$ instead of $\tau \circ \sigma$ ). Note that we have $E(\sigma \tau)=(E \sigma) \tau$.


## Exercise

Suppose we have two substitutions

$$
\begin{aligned}
& \left\{x_{1} \mapsto s_{1}, \ldots, x_{m} \mapsto s_{m}\right\} \text { and } \\
& \left\{y_{1} \mapsto t_{1}, \ldots, y_{n} \mapsto t_{n}\right\} .
\end{aligned}
$$

How can we write their composition using the same notation?

## Instance

An instance of an expression (that is term, atom, literal, or clause) $E$ is obtained by applying a substitution to $E$.
> some instances of the term $f(x, a, g(x))$ are:

- but the term $f(b, a, g(c))$ is not an instance of this term.


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## Herbrand's Theorem

For a set of clauses $S$ denote by $S^{*}$ the set of ground instances of clauses in $S$.

Theorem (Herbrand)
Let $S$ be a set of clauses. The following conditions are equivalent S is unsatisfiable; 2. $S^{*}$ is unsatisfiable; Note that hy comnactness the last condition is equivalent to there exists a finite unsatisfiable set of ground instances of clauses in $S$

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## Lifting

Lifting is a technique for proving completeness theorems in the following way:

1. Prove completeness of the system for a set of ground clauses;
2. Lift the proof to the non-ground case.

## Lifting, Example

Consider two (non-ground) clauses $p(x, a) \vee q_{1}(x)$ and $\neg p(y, z) \vee q_{2}(y, z)$. If the signature contains function symbols, then both clauses have infinite sets of instances:

$$
\begin{array}{r|l}
\left\{p(r, a) \vee q_{1}(r)\right. & r \text { is ground }\} \\
\left\{\neg p(s, t) \vee q_{2}(s, t)\right. & s, t \text { are ground }\}
\end{array}
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We can resolve such instances if and only if $r=s$ and $t=a$. Then we can apply the following inference


But there is an infinite number of such inferences.

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\frac{p(s, a) \vee q_{1}(s) \neg p(s, a) \vee q_{2}(s, a)}{q_{1}(s) \vee q_{2}(s, a)}(\mathrm{BR})
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## Lifting, Idea

The idea is to represent an infinite number of ground inferences of the form

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Is this always possible? Yes!

$$
\begin{equation*}
\frac{p(x, a) \vee q_{1}(x) \neg p(y, z) \vee q_{2}(y, z)}{q_{1}(y) \vee q_{2}(y, a)} \tag{BR}
\end{equation*}
$$

Note that the substitution $\{x \mapsto y, z \mapsto a\}$ is a solution of the "equation" $p(x, a)=p(y, z)$.

## What should we lift?

- Selection function $\sigma$.
- Calculus $\mathbb{B}_{\mathbb{R}_{\sigma}}$.
- Ordering $\succ$, if we use ordered resolution.

Most importantly, for the lifting to work we should be able to solve equations $s=t$ between terms and between atoms.

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## Unifier

Unifier of expressions $s_{1}$ and $s_{2}$ : a substitution $\theta$ such that $s_{1} \theta=s_{2} \theta$. In other words, a unifier is a solution to an "equation" $s_{1}=s_{2}$. In a similar way we can define solutions to systems of equations $s_{1}=s_{1}^{\prime}, \ldots, s_{n}=s_{n}^{\prime}$. We call such solutions simultaneous unifiers of $s_{1}, \ldots, s_{n}$ and

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## (Most General) Unifiers

A solution $\theta$ to a set of equations $E$ is said to be a most general solution if for every other solution $\sigma$ there exists a substitution $\tau$ such that $\theta \tau=\sigma$.
In a similar way can define a most general unifier.
Consider terms $f\left(x_{1}, g\left(x_{1}\right), x_{2}\right)$ and $f\left(y_{1}, y_{2}, y_{2}\right)$.
(Some of) their unifiers are
$\theta_{1}=\left\{y_{1} \mapsto x_{1}, y_{2} \mapsto g\left(x_{1}\right), x_{2} \mapsto g\left(x_{1}\right)\right\}$ and
$\theta_{2}=\left\{y_{1} \mapsto a, y_{2} \mapsto g(a), x_{2} \mapsto g(a), x_{1} \mapsto a\right\}:$
$f\left(x_{1}, g\left(x_{1}\right), x_{2}\right) \theta_{1}=f\left(x_{1}, g\left(x_{1}\right), g\left(x_{1}\right)\right)$;
$f\left(y_{1}, y_{2}, y_{2}\right) \theta_{1}=f\left(x_{1}, g\left(x_{1}\right), g\left(x_{1}\right)\right)$;
$f\left(x_{1}, g\left(x_{1}\right), x_{2}\right) \theta_{2}=f(a, g(a), g(a)) ;$
$f\left(y_{1}, y_{2}, y_{2}\right) \theta_{2}=f(a, g(a), g(a))$.
But only $\theta_{1}$ is most general.

## Unification

Let $E$ be a set of equations. An isolated equation in $E$ is any equation $x=t$ in it such that $x$ has exactly one occurrence in $E$.
input: a finite set of equations $E$
output: a solution to $E$ or failure.

## begin

while there exists a non-isolated equation $(s=t) \in E \underline{\text { do }}$

## case $(s, t)$ of

$(t, t) \Rightarrow$ remove this equation from $E$
$(x, t) \Rightarrow$ if $x$ occurs in $t$ then halt with failure
else replace $x$ by $t$ in all other equations of $E$
$(t, x) \Rightarrow$ replace this equation by $x=t$
and do the same as in the case $(x, t)$
$(c, d) \Rightarrow$ halt with failure
$\left(c, f\left(t_{1}, \ldots, t_{n}\right)\right) \Rightarrow$ halt with failure
$\left(f\left(t_{1}, \ldots, t_{n}\right), c\right) \Rightarrow$ halt with failure
$\left(f\left(s_{1}, \ldots, s_{m}\right), g\left(t_{1}, \ldots, t_{n}\right)\right) \Rightarrow$ halt with failure
$\left(f\left(s_{1}, \ldots, s_{n}\right), f\left(t_{1}, \ldots, t_{n}\right)\right) \Rightarrow$ replace this equation by the set

$$
s_{1}=t_{1}, \ldots, s_{n}=t_{n}
$$

end while
Now $E$ has the form $\left\{x_{1}=r_{1}, \ldots, x_{l}=r_{l}\right\}$ and every equation in it is isolated return the substitution $\left\{x_{1} \mapsto r_{1}, \ldots, x_{l} \mapsto r_{1}\right\}$
end

## Examples

$$
\begin{aligned}
& \{h(g(f(x), a))=h(g(y, y))\} \\
& \{h(f(y), y, f(z))=h(z, f(x), x)\} \\
& \{h(g(f(x), z))=h(g(y, y))\}
\end{aligned}
$$

## Occurs check

- The check " $x$ occurs in $t$ " is called an occurs check.
- In Prolog, the predicate = implements unification without occurs check.
- There is also a predicate (and a command) for unification with occurs check.


## Properties

Theorem Suppose we run the unification algorithm on $s=t$. Then

- If $s$ and $t$ are unifiable, then the algorithms terminates and outputs a most general unifier of $s$ and $t$.
- If $s$ and $t$ are not unifiable, then the algorithms terminates with failure.
Notation (slightly ambiguous):
- mgu( $s, t$ ) for a most general unifier;
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## Exercise

Consider a trivial system of equations $\}$ or $\{a=a\}$.
Which substitutions are solutions to it?
What is the set of most general solutions to it?

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## Properties

Theorem
Let $C$ be a clause and $E$ a set of equations. Then
$\left\{D \in C^{*} \mid \exists \theta(C \theta=D\right.$ and $\theta$ is a solution to $\left.E)\right\}=(\operatorname{Cmgs}(E))^{*}$.

## Binary Resolution System, Non-Ground Case

Binary resolution is the following inference rule:

$$
\frac{\underline{A} \vee C \underset{(C \vee D) m g u(A, B)}{(\mathrm{BR})}, \text {, }, \text {, }}{\underline{B} \vee D}
$$

Factoring is the following inference rule:

$$
\frac{\underline{A} \vee \underline{B} \vee C}{(A \vee C) m g u(A, B)}(\text { Fact })
$$

## Soundness and Completeness

$\mathbb{B} \mathbb{R}$ is sound and complete, that is, if a set of clauses is unsatisfiable, then one can derive an empty clause from this set.

Soundness is evident since the conclusion of any inference rule is a logical consequence of its premises.

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Binary resolution with arbitrary selection is incomplete.
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## A problem

Is the following set of clauses unsatisfiable?

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& p(x, a) \\
& \neg p(b, x) ?
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## Renaming away

The domain of a substitution $\theta$ is the set of variables $\{x \mid \theta(x) \neq x\}$ is finite.
The range of $\theta$ is the set of terms $\{x \theta \mid x \theta \neq x\}$.

A substitution $\theta$ is called renaming if (three equivalent characterisations)
$\rightarrow$ the domain of $\theta$ coincides with its range.

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- there exists an $n$ such that $\theta^{n}=\{ \}$.

A variant of a term (atom, literal, clause) $t$ is any term obtained from $t$ by appying a renaming.

## Hidden rule: renaming away

Renaming $E_{1}$ away from $E_{2}$ : replace $E_{1}$ by its variant $E_{1}^{\prime}$ so that $E_{1}^{\prime}$ and $E_{2}$ have no common variables.

Before applying resolution to two clauses $C_{1}$ and $C_{2}$ we should always rename $C_{1}$ away from $C_{2}$.

Renaming is sometimes called standardising apart (especially in the
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## Example

(1) $\neg p(x) \vee \neg q(y) \quad$ input
(2) $\neg p(x) \vee q(y)$ input
(3) $p(x) \vee \neg q(y) \quad$ input
(4) $p(x) \vee q(y) \quad$ input
(5) $\neg p(x) \vee \neg p(y) \quad \mathrm{BR} \quad(1,2)$
(6) $\neg p(x)$

Fact
(5)
(7) $p(x) \vee p(y) \quad \mathrm{BR}$
$(3,4)$
(8) $p(x)$

Fact
(7)
(9) $\square$

BR
$(6,8)$

