$A = \forall x \forall y (q(x, y) \rightarrow (p(x, y) \lor \exists z (p(x, z) \land q(z, y)))$ 

Take the tructure  $M = (people, \{q \mapsto ancestor, p \mapsto parent\}, \emptyset, \emptyset)$  and any value assignment *s*:

- ►  $v_{M,s}(\forall x \forall y(q(x,y) \rightarrow (p(x,y) \lor \exists z(p(x,z) \land q(z,y))))) = 1$  iff
- ► for all  $d \in D$ ,  $v_{M,s[x \leftarrow d]}(\forall y(q(x, y) \rightarrow (p(x, y) \lor \exists z(p(x, z) \land q(z, y))))) = 1$  iff
- ► for all  $d \in D$ , for all  $d' \in D$ ,  $v_{M,s[x \leftarrow d][y \leftarrow d']}(q(x, y) \rightarrow (p(x, y) \lor \exists z(p(x, z) \land q(z, y)))) = 1$  iff
- ► for all  $d \in D$ , for all  $d' \in D$ , if  $v_{M,s[x \mapsto d][y \mapsto d']}(q(x, y)) = 1$ then  $v_{M,s[x \mapsto d][y \mapsto d']}(p(x, y) \lor \exists z(p(x, z) \land q(z, y))) = 1$  iff
- ► for all  $d \in D$ , for all  $d' \in D$ , if  $(d, d') \in ancestor$  then either  $v_{M,s[x \mapsto d][y \mapsto d']}(p(x, y))$  or  $v_{M,s[x \mapsto d][y \mapsto d']}(\exists z(p(x, z) \land q(z, y)))$  iff
- ▶ for all  $d \in D$ , for all  $d' \in D$ , if  $(d, d') \in ancestor$  then either  $(d, d') \in parent$  or there exists a  $d'' \in D$ , such that  $v_{M,s[x \mapsto d][y \mapsto d'][z \mapsto d'']}(p(x, z) \land q(z, y)) = 1$  iff
- ▶ for all  $d \in D$ , for all  $d' \in D$ , if  $(d, d') \in ancestor$  then either  $(d, d') \in parent$  or there exists a  $d'' \in D$ , such that  $v_{M,s[x \mapsto d][y \mapsto d'][z \mapsto d'']}(p(x, z)) = 1$  and  $v_{M,s[x \mapsto d][y \mapsto d'][z \mapsto d'']}(q(z, y)) = 1$ iff
- ▶ for all  $d \in D$ , for all  $d' \in D$ , if  $(d, d') \in ancestor$  then either  $(d, d') \in parent$  or there exists a  $d'' \in D$ , such that  $(d \neq d'') \in parent$  and  $e \in C$ .

#### Literal, clause

- Literal: either an atom p (positive literal) or its negation ¬p (negative literal).
- The complementary literal to L:

 $\overline{L} \stackrel{\text{def}}{\Leftrightarrow} \left\{ \begin{array}{ll} \neg L, & \text{if } L \text{ is positive;} \\ p, & \text{if } L \text{ has the form } \neg p. \end{array} \right.$ 

In other words, p and  $\neg p$  are complementary.

- Clause: a disjunction  $L_1 \vee \ldots \vee L_n$ ,  $n \ge 0$  of literals.
- ► Empty clause, denoted by □: n = 0 (the empty clause is false in every interpretation).

• Unit clause: n = 1.

When we consider clauses we assume that the order of literals in them is irrelevant.

## **Negation Normal Form**

# A formula *A* is in negation normal form, or simply NNF, if it is either $\top$ , or $\bot$ , or is built from literals using only $\land$ , $\lor$ , $\forall$ and $\exists$ .

A formula B is called a negation normal form of a formula A if B is equivalent to A and B is in negation normal form.



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## NNF transformation

$$\begin{array}{rcl} A \leftrightarrow B & \Rightarrow & (\neg A \lor B) \land (\neg B \lor A), \\ A \rightarrow B & \Rightarrow & \neg A \lor B, \\ \neg (A \land B) & \Rightarrow & \neg A \lor \neg B, \\ \neg (A \lor B) & \Rightarrow & \neg A \land \neg B, \\ \neg (\forall x)A & \Rightarrow & (\exists x) \neg A, \\ \neg (\exists x)A & \Rightarrow & (\forall x) \neg A, \\ \neg \neg A & \Rightarrow & A \end{array}$$

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## **Rectified formulas**

#### Rectified formula F:

- no variable appears both free and bound in F;
- For every variable x, the formula F contains at most one occurrence of quantifiers ∀x or ∃x.

Any formula can be transformed into a rectified formula by renaming bound variables.

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#### **Rectification: Example**

$$p(x) \to \exists x (p(x) \land \forall x (p(x) \lor r \to \neg p(x))) \Rightarrow$$
  

$$p(x) \to \exists x_1 (p(x_1) \land \forall x (p(x) \lor r \to \neg p(x))) \Rightarrow$$
  

$$p(x) \to \exists x_1 (p(x_1) \land \forall x_2 (p(x_2) \lor r \to \neg p(x_2)))$$

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# **Skolemisation: Choice Functions**

We would like to get rid of existential quantifiers using choice functions, or witness functions. Consider an example. We know that every tree has a root:

 $\forall x(tree(x) \to \exists y(root(y, x))). \quad (*)$ 

Then we can introduce a function, say *rootof* that gives the root of a tree and write

 $\forall x (tree(x) \rightarrow root(rootof(x), x)).$  (

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Note that (\*) is a logical consequence of (\*\*).

## Skolemisation

Let *A* be a closed rectified formula in NNF and  $(\exists x)B$  be a subformula of *A*. Let  $(\forall x_1), \ldots, (\forall x_n)$  be all universal quantifiers such that  $(\exists x)B$  is in the scope of these quantifiers. Then:

- 1. remove  $(\exists x)$  from *A*.
- 2. replace x everywhere in A by  $f(x_1, ..., x_n)$ , where f is a new function symbol.

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Skolemisation does not preserve equivalence but preserves satisfiability.

# **CNF** Transformation

Take a first-order formula *F*.

- 1. transform it into NNF;
- 2. rectify it;
- 3. skolemise it;
- 4. remove all universal quantifiers;
- 5. transform to CNF the same way as propositional formulas.

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#### Universal closure of a formula A is a formula

 $(\forall x_1) \dots (\forall x_n) A$ ,

#### denoted by $\forall A$ , where $x_1, \ldots, x_n$ are all free variables of A.

CNF transformation transforms a closed formula F into a set of clauses  $C_1, \ldots, C_n$  such that F is satisfiable if and only if so is the set of formulas  $\forall C_1, \ldots, \forall C_n$ .

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#### Suppose we want to prove (establish validity of)

#### $(\exists y)(\forall x)p(x,y) \rightarrow (\forall x)(\exists y)p(x,y).$

It is valid if and only if its negation

 $\neg((\exists y)(\forall x)p(x,y) \rightarrow (\forall x)(\exists y)p(x,y))$ 

is unsatisfiable.

The transformation of this formula to CNF gives us two clauses:

p(x,a) ¬p(b,y).

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 $(\forall x)p(x,a)$  $(\forall y)\neg p(b,y)?$ 

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- Since we have  $(\forall x)p(x, a)$ , we also have p(b, a);
- Since we have  $(\forall y) \neg p(b, y)$ , we also have  $\neg p(b, a)$ ;
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Note that we established unsatisfiability by

- Substituting terms for variables, e.g. *b* for *x* in p(x, a);
- Using propositional resolution.

Are these two ingredients sufficient to have a complete procedure?

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A substitution θ is a mapping from variables to terms such that the set {x | θ(x) ≠ x} is finite.

• This set is called the domain of  $\theta$ .

▶ Notation:  $\{x_1 \mapsto t_1, \ldots, x_n \mapsto t_n\}$ , where  $x_1, \ldots, x_n$  are pairwise different variables, denotes the substitution  $\theta$  such that

$$\theta(x) = \begin{cases} t_i & \text{if } x = x_i; \\ x & \text{if } x \notin \{x_1, \dots, x_n\}. \end{cases}$$

- Application of this substitution to an expression E: simultaneous replacement of x<sub>i</sub> by t<sub>i</sub>.
- The result of the application of a substitution  $\theta$  to *E* is denoted by  $E\theta$ .
- Since substitutions are functions, we can define their composition (writen  $\sigma \tau$  instead of  $\tau \circ \sigma$ ). Note that we have  $E(\sigma \tau) = (E\sigma)\tau$ .

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#### Exercise

Suppose we have two substitutions

$$\{x_1 \mapsto s_1, \dots, x_m \mapsto s_m\}$$
 and  
 $\{y_1 \mapsto t_1, \dots, y_n \mapsto t_n\}.$ 

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How can we write their composition using the same notation?

# An instance of an expression (that is term, atom, literal, or clause) E is obtained by applying a substitution to E. Examples:

some instances of the term f(x, a, g(x)) are: f(x, a, g(x)), f(y, a, g(y)), f(a, a, g(a)), f(g(b), a, g(g(b)));

but the term f(b, a, g(c)) is not an instance of this term.

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For a set of clauses S denote by  $S^*$  the set of ground instances of clauses in S.

#### Theorem (Herbrand)

Let S be a set of clauses. The following conditions are equivalent.

- 1. *S is unsatisfiable;*
- 2. S\* is unsatisfiable;

Note that by compactness the last condition is equivalent to

3. there exists a finite unsatisfiable set of ground instances of clauses in *S*.

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The theorem reduces the problem of checking inconsistency of sets of arbitrary clauses to checking inconsistency of sets of ground clauses ... the only problem is that  $S^*$  can be infinite even if S is finite.

Lifting is a technique for proving completeness theorems in the following way:

1. Prove completeness of the system for a set of ground clauses;

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2. Lift the proof to the non-ground case.

# Lifting, Example

Consider two (non-ground) clauses  $p(x, a) \lor q_1(x)$  and  $\neg p(y, z) \lor q_2(y, z)$ . If the signature contains function symbols, then both clauses have infinite sets of instances:

 $\{ p(r, a) \lor q_1(r) \mid r \text{ is ground} \} \\ \{ \neg p(s, t) \lor q_2(s, t) \mid s, t \text{ are ground} \}$ 

We can resolve such instances if and only if r = s and t = a. Then we can apply the following inference

$$\frac{p(s,a) \lor q_1(s) \quad \neg p(s,a) \lor q_2(s,a)}{q_1(s) \lor q_2(s,a)}$$
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### Lifting, Idea

The idea is to represent an infinite number of ground inferences of the form

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by a single non-ground inference

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Is this always possible? Yes!

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Note that the substitution  $\{x \mapsto y, z \mapsto a\}$  is a solution of the "equation" p(x, a) = p(y, z).

#### What should we lift?

- Selection function σ.
- Calculus  $\mathbb{BR}_{\sigma}$ .
- ► Ordering ≻, if we use ordered resolution.

Most importantly, for the lifting to work we should be able to solve equations s = t between terms and between atoms.

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#### Unifier

#### Unifier of expressions $s_1$ and $s_2$ : a substitution $\theta$ such that $s_1\theta = s_2\theta$ .

In other words, a unifier is a solution to an "equation"  $s_1 = s_2$ .

In a similar way we can define solutions to systems of equations  $s_1 = s'_1, \ldots, s_n = s'_n$ . We call such solutions simultaneous unifiers of  $s_1, \ldots, s_n$  and  $s'_1, \ldots, s'_n$ .

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### (Most General) Unifiers

A solution  $\theta$  to a set of equations E is said to be a most general solution if for every other solution  $\sigma$  there exists a substitution  $\tau$  such that  $\theta \tau = \sigma$ . In a similar way can define a most general unifier. Consider terms  $f(x_1, g(x_1), x_2)$  and  $f(y_1, y_2, y_2)$ . (Some of) their unifiers are  $\theta_1 = \{ v_1 \mapsto x_1, v_2 \mapsto g(x_1), x_2 \mapsto g(x_1) \}$  and  $\theta_2 = \{ v_1 \mapsto a, v_2 \mapsto g(a), x_2 \mapsto g(a), x_1 \mapsto a \}$ :  $f(x_1, g(x_1), x_2)\theta_1 = f(x_1, g(x_1), g(x_1));$  $f(y_1, y_2, y_2)\theta_1 = f(x_1, q(x_1), q(x_1));$  $f(x_1, g(x_1), x_2)\theta_2 = f(a, g(a), g(a));$  $f(y_1, y_2, y_2)\theta_2 = f(a, g(a), g(a)).$ But only  $\theta_1$  is most general.

### Unification

Let E be a set of equations. An isolated equation in E is any equation x = tin it such that x has exactly one occurrence in E.

**input**: a finite set of equations *E* output: a solution to *E* or failure. begin while there exists a non-isolated equation  $(s = t) \in E$  do case (s, t) of  $(t, t) \Rightarrow$  remove this equation from E  $(x, t) \Rightarrow$  if x occurs in t then halt with failure else replace x by t in all other equations of E  $(t, x) \Rightarrow$  replace this equation by x = tand do the same as in the case (x, t) $(c, d) \Rightarrow$  halt with failure  $(c, f(t_1, \ldots, t_n)) \Rightarrow$  halt with failure  $(f(t_1,\ldots,t_n),c) \Rightarrow$  halt with failure  $(f(s_1,\ldots,s_m),g(t_1,\ldots,t_n)) \Rightarrow$  halt with failure  $(f(s_1,\ldots,s_n), f(t_1,\ldots,t_n)) \Rightarrow$  replace this equation by the set  $S_1 = t_1 \ldots S_n = t_n$ 

#### end while

Now *E* has the form  $\{x_1 = r_1, \ldots, x_l = r_l\}$  and every equation in it is isolated **return** the substitution  $\{x_1 \mapsto r_1, \ldots, x_l \mapsto r_l\}$ 

#### end

## Examples

$$\{ h(g(f(x), a)) = h(g(y, y)) \} \\ \{ h(f(y), y, f(z)) = h(z, f(x), x) \} \\ \{ h(g(f(x), z)) = h(g(y, y)) \}$$

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#### Occurs check

- ► The check "*x* occurs in *t*" is called an occurs check.
- In Prolog, the predicate = implements unification without occurs check.
- There is also a predicate (and a command) for unification with occurs check.

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#### **Properties**

**Theorem** Suppose we run the unification algorithm on s = t. Then

- If s and t are unifiable, then the algorithms terminates and outputs a most general unifier of s and t.
- ► If *s* and *t* are not unifiable, then the algorithms terminates with failure.

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Notation (slightly ambiguous):

- mgu(s, t) for a most general unifier;
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#### Consider a trivial system of equations $\{\}$ or $\{a = a\}$ .

Which substitutions are solutions to it?

What is the set of most general solutions to it?



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What is the set of most general solutions to it?

#### **Properties**

#### Theorem Let *C* be a clause and *E* a set of equations. Then

 $\{D \in C^* \mid \exists \theta (C\theta = D \text{ and } \theta \text{ is a solution to } E)\} = (Cmgs(E))^*.$ 

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#### Binary Resolution System, Non-Ground Case

Binary resolution is the following inference rule:

$$\frac{\underline{A} \lor C \quad \underline{\neg B} \lor D}{(C \lor D)mgu(A, B)}$$
(BR),

Factoring is the following inference rule:

$$\frac{\underline{A} \vee \underline{B} \vee C}{(A \vee C)mgu(A, B)}$$
(Fact),

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 $\mathbb{BR}$  is sound and complete, that is, if a set of clauses is unsatisfiable, then one can derive an empty clause from this set.

Soundness is evident since the conclusion of any inference rule is a logical consequence of its premises.

Completeness can be proved using completeness of propositional resolution and lifting.

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#### Ordered resolution?

#### Binary resolution with arbitrary selection is incomplete.

To define ordered resolution one has to define ordering for non-ground clauses in a way so that they also work for their ground instances.



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### A problem

#### Is the following set of clauses unsatisfiable?

p(x, a) $\neg p(b, x)?$ 

Yes, since clauses denote their universal closures:

 $(\forall x)p(x,a)$  $(\forall x)\neg p(b,x).$ 

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#### Renaming away

The domain of a substitution  $\theta$  is the set of variables  $\{x \mid \theta(x) \neq x\}$  is finite. The range of  $\theta$  is the set of terms  $\{x\theta \mid x\theta \neq x\}$ .

A substitution  $\theta$  is called renaming if (three equivalent characterisations)

- the domain of  $\theta$  coincides with its range.
- $\theta$  has an inverse  $\sigma$  (that is,  $\theta \circ \sigma = \sigma \circ \theta = \{\}$ ).
- there exists an *n* such that  $\theta^n = \{\}$ .

A variant of a term (atom, literal, clause) t is any term obtained from t by appying a renaming.

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A variant of a term (atom, literal, clause) t is any term obtained from t by appying a renaming.

### Hidden rule: renaming away

# Renaming $E_1$ away from $E_2$ : replace $E_1$ by its variant $E'_1$ so that $E'_1$ and $E_2$ have no common variables.

Before applying resolution to two clauses  $C_1$  and  $C_2$  we should always rename  $C_1$  away from  $C_2$ .

Renaming is sometimes called standardising apart (especially in the logic programming literature).

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## Example

(1) 
$$\neg p(x) \lor \neg q(y)$$
 input  
(2)  $\neg p(x) \lor q(y)$  input  
(3)  $p(x) \lor \neg q(y)$  input  
(4)  $p(x) \lor q(y)$  input  
(5)  $\neg p(x) \lor \neg p(y)$  BR  
(6)  $\neg p(x)$  Fact  
(7)  $p(x) \lor p(y)$  BR  
(8)  $p(x)$  Fact  
(9)  $\Box$  BR

(1,2) (5) (3,4)

(7) (6,8)